

Rexroth IndraControl VCP 08

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Project Planning Manual



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System Presentation

1 System Presentation

1.1 Brief Description of the VCP 08

The small operator terminal VCP 08 is a machine operator terminal which can initiate functions in the machine as defined in the application.

Special features of the VCP 08 are its compact design and the seal running around the rear. Thus, it is suitable for various applications. Furthermore, every mounting position is possible.

Depending on the variant, the small operator terminal is equipped either with three serial standard interfaces or with a field bus interface.

The front panel with short-stroke keyboard consists of a 3 mm aluminium plate with tapered edges and is covered by a chemical resistive polyester foil with embossed key areas.



Fig. 1-1: VCP 08 with keyboard

System Presentation

1.2 Operating System

A special operating system is installed on the small operator terminal. If necessary, this operating system can be reloaded into the device (firmware download). This can be done with the associated programming software "VI Composer".

1.3 Commissioning

Mount the device properly (for more information, see chapter Dimensions). Then connect the device to the voltage supply and to the control unit or the field bus system, if required.

Important Directions for Use

2 Important Directions for Use

2.1 Appropriate Use

2.1.1 Introduction

Rexroth products represent state-of-the-art developments and manufacturing. They are tested prior to delivery to ensure operating safety and reliability.

The products may only be used in the manner that is defined as appropriate. If they are used in an inappropriate manner, then situations can develop that may lead to property damage or injury to personnel.



Bosch Rexroth, as manufacturer, is not liable for any damages resulting from inappropriate use. In such cases, the guarantee and the right to payment of damages resulting from inappropriate use are forfeited. The user alone carries all responsibility of the risks.

Before using Rexroth products, make sure that all the pre-requisites for appropriate use of the products are satisfied:

- Personnel that in any way, shape or form uses our products must first read and understand the relevant safety instructions and be familiar with appropriate use.
- If the product takes the form of hardware, then they must remain in their original state, in other words, no structural changes are permitted. It is not permitted to decompile software products or alter source codes.
- Do not mount damaged or faulty products or use them in operation.
- Make sure that the products have been installed in the manner described in the relevant documentation.

Important Directions for Use

2.1.2 Areas of Use and Application

The small operator terminal VCP 08 made by Bosch Rexroth allows to operate and control machines and installations and serves to visualize the information on the machine/installation to be operated required by the user.



The VCP 08 may only be used with the accessories and parts specified in this document. If a component has not been specifically named, then it may not be either mounted or connected. The same applies to cables and lines.

Operation is only permitted in the specified configurations and combinations of components using the software and firmware as specified in the relevant function descriptions.

The small operator terminals VCP 08 have been developed for use in single or multiple-axis control tasks.

Typical applications of the VCP 08 are:

- Handling and assembly systems,
- · Packaging machines,
- · Printing and paper processing machines and
- · Machine tools.

The VCP 08 may only be operated under the assembly, installation and ambient conditions as described here (temperature, system of protection, humidity, EMC requirements, etc.) and in the position specified.

2.2 Inappropriate Use

Using the small operator terminal outside of the above-referenced areas of application or under operating conditions other than described in the document and the technical data specified is defined as "inappropriate use".

The small operator terminal may not be used, if

- they are subject to operating conditions that do not meet the above specified ambient conditions. This includes, for example, operation under water, in the case of extreme temperature fluctuations or extremely high maximum temperatures or if
- Bosch Rexroth has not specifically released them for that intended purpose. Please note the specifications outlined in the general Safety Guidelines!

3 Safety Instructions for Electric Drives and Controls

3.1 Introduction

Read these instructions before the initial startup of the equipment in order to eliminate the risk of bodily harm or material damage. Follow these safety instructions at all times. Do not attempt to install or start up this equipment without first reading all documentation provided with the product. Read and understand these safety instructions and all user documentation of the equipment prior to working with the equipment at any time. If you do not have the user documentation for your equipment, contact your local Bosch Rexroth representative to send this documentation immediately to the person or persons responsible for the safe operation of this equipment. If the equipment is resold, rented or transferred or passed on to others, then these safety instructions must be delivered with the equipment.



WARNING

Improper use of this equipment, failure to follow the safety instructions in this document or tampering with the product, including disabling of safety devices, may result in material damage, bodily harm, electric shock or even death!

3.2 Explanations

The safety instructions describe the following degrees of hazard seriousness in compliance with ANSI Z535. The degree of hazard seriousness informs about the consequences resulting from non-compliance with the safety instructions.

Warning symbol	Signal word and degree of hazard seriousness according to ANSI
<u>^!</u>	DANGER Death or severe bodily harm will occur.
<u>^</u>	WARNING Death or severe bodily harm may occur.
	CAUTION Bodily harm or material damage may occur.

Fig. 3-1: Hazard classification (according to ANSI Z535)

3.3 Hazards by Improper Use



DANGER

High voltage and high discharge current! Danger to life or severe bodily harm by electric shock!



DANGER

Dangerous movements! Danger to life, severe bodily harm or material damage by unintentional motor movements!



WARNING

High electrical voltage due to wrong connections! Danger to life or bodily harm by electric shock!



WARNING

Health hazard for persons with heart pacemakers, metal implants and hearing aids in proximity to electrical equipment!



CAUTION

Surface of machine housing could be extremely hot! Danger of injury! Danger of burns!



CAUTION

Risk of injury due to improper handling! Bodily harm caused by crushing, shearing, cutting and mechanical shock or incorrect handling of pressurized systems!



CAUTION

Risk of injury due to incorrect handling of batteries!

3.4 General Information

- Bosch Rexroth AG is not liable for damages resulting from failure to observe the warnings provided in this documentation.
- Read the operating, maintenance and safety instructions in your language before starting up the machine. If you find that you cannot completely understand the documentation for your product, please ask your supplier to clarify.
- Proper and correct transport, storage, assembly and installation as well as care in operation and maintenance are prerequisites for optimal and safe operation of this equipment.
- Only persons who are trained and qualified for the use and operation
 of the equipment may work on this equipment or within its proximity.

- Furthermore, they must be trained, instructed and qualified to switch electrical circuits and equipment on and off in accordance with technical safety regulations, to ground them and to mark them according to the requirements of safe work practices. They must have adequate safety equipment and be trained in first aid.
- Only use spare parts and accessories approved by the manufacturer
- Follow all safety regulations and requirements for the specific application as practiced in the country of use.
- The equipment is designed for installation in industrial machinery.
- The ambient conditions given in the product documentation must be observed.
- Use only safety features and applications that are clearly and explicitly approved in the Project Planning Manual.
- For example, the following areas of use are not permitted: construction cranes, elevators used for people or freight, devices and vehicles to transport people, medical applications, refinery plants, transport of hazardous goods, nuclear applications, applications sensitive to high frequency, mining, food processing, control of protection equipment (also in a machine).
- The information given in the documentation of the product with regard to the use of the delivered components contains only examples of applications and suggestions.

The machine and installation manufacturer must

- make sure that the delivered components are suited for his individual application and check the information given in this documentation with regard to the use of the components,
- make sure that his application complies with the applicable safety regulations and standards and carry out the required measures, modifications and complements.
- Startup of the delivered components is only permitted once it is sure that the machine or installation in which they are installed complies with the national regulations, safety specifications and standards of the application.
- Operation is only permitted if the national EMC regulations for the application are met.
- The instructions for installation in accordance with EMC requirements can be found in the documentation "EMC in Drive and Control Systems".
- Technical data, connections and operational conditions are specified in the product documentation and must be followed at all times.

The machine or installation manufacturer is responsible for compliance with the limiting values as prescribed in the national regulations.

 Technical data, connections and operational conditions are specified in the product documentation and must be followed at all times.

3.5 Protection Against Contact with Electrical Parts



This section refers to equipment and drive components with voltages above 50 Volts.

Touching live parts with voltages of 50 Volts and more with bare hands or conductive tools or touching ungrounded housings can be dangerous and cause electric shock. In order to operate electrical equipment, certain parts must unavoidably have dangerous voltages applied to them.



DANGER

High electrical voltage! Danger to life, severe bodily harm by electric shock!

- Only those trained and qualified to work with or on electrical equipment are permitted to operate, maintain or repair this equipment.
- Follow general construction and safety regulations when working on high voltage installations.
- Before switching on power the ground wire must be permanently connected to all electrical units according to the connection diagram.
- Do not operate electrical equipment at any time, even for brief measurements or tests, if the ground wire is not permanently connected to the points of the components provided for this purpose.
- Before working with electrical parts with voltage higher than 50 V, the
 equipment must be disconnected from the mains voltage or power
 supply. Make sure the equipment cannot be switched on again unintended.
- The following should be observed with electrical drive and filter components:

Wait five (5) minutes after switching off power to allow capacitors to discharge before beginning to work. Measure the voltage on the capacitors before beginning to work to make sure that the equipment is safe to touch.

- Never touch the electrical connection points of a component while power is turned on.
- Install the covers and guards provided with the equipment properly before switching the equipment on. Prevent contact with live parts at any time.
- A residual-current-operated protective device (RCD) must not be used on electric drives! Indirect contact must be prevented by other means, for example, by an overcurrent protective device.
- Electrical components with exposed live parts and uncovered high voltage terminals must be installed in a protective housing, for example, in a control cabinet.

To be observed with electrical drive and filter components:



DANGER

High electrical voltage on the housing! High leakage current! Danger to life, danger of injury by electric shock!

- Connect the electrical equipment, the housings of all electrical units and motors permanently with the safety conductor at the ground points before power is switched on. Look at the connection diagram. This is even necessary for brief tests.
- Connect the safety conductor of the electrical equipment always permanently and firmly to the supply mains. Leakage current exceeds 3.5 mA in normal operation.
- Use a copper conductor with at least 10 mm² cross section over its entire course for this safety conductor connection!
- Prior to startups, even for brief tests, always connect the protective conductor or connect with ground wire. Otherwise, high voltages can occur on the housing that lead to electric shock.

3.6 Protection Against Electric Shock by Protective Low Voltage (PELV)

All connections and terminals with voltages between 0 and 50 Volts on Rexroth products are protective low voltages designed in accordance with international standards on electrical safety.



WARNING

High electrical voltage due to wrong connections! Danger to life, bodily harm by electric shock!

- Only connect equipment, electrical components and cables of the protective low voltage type (PELV = Protective Extra Low Voltage) to all terminals and clamps with voltages of 0 to 50 Volts.
- Only electrical circuits may be connected which are safely isolated against high voltage circuits. Safe isolation is achieved, for example, with an isolating transformer, an opto-electronic coupler or when battery-operated.

3.7 Protection Against Dangerous Movements

Dangerous movements can be caused by faulty control of the connected motors. Some common examples are:

- · improper or wrong wiring of cable connections
- incorrect operation of the equipment components
- · wrong input of parameters before operation
- malfunction of sensors, encoders and monitoring devices
- defective components
- · software or firmware errors

Dangerous movements can occur immediately after equipment is switched on or even after an unspecified time of trouble-free operation.

The monitoring in the drive components will normally be sufficient to avoid faulty operation in the connected drives. Regarding personal safety, especially the danger of bodily injury and material damage, this alone cannot be relied upon to ensure complete safety. Until the integrated monitoring functions become effective, it must be assumed in any case that faulty drive movements will occur. The extent of faulty drive movements depends upon the type of control and the state of operation.



DANGER

Dangerous movements! Danger to life, risk of injury, severe bodily harm or material damage!

 Ensure personal safety by means of qualified and tested higher-level monitoring devices or measures integrated in the installation. Unintended machine motion is possible if monitoring devices are disabled, bypassed or not activated.

Pay attention to unintended machine motion or other malfunction in any mode of operation.

- Keep free and clear of the machine's range of motion and moving parts. Possible measures to prevent people from accidentally entering the machine's range of motion:
- use safety fences
- use safety guards
- use protective coverings
- install light curtains or light barriers

- Fences and coverings must be strong enough to resist maximum possible momentum, especially if there is a possibility of loose parts flying off.
- Mount the emergency stop switch in the immediate reach of the operator. Verify that the emergency stop works before startup. Don't operate the machine if the emergency stop is not working.
- Isolate the drive power connection by means of an emergency stop circuit or use a starting lockout to prevent unintentional start.
- Make sure that the drives are brought to a safe standstill before accessing or entering the danger zone. Safe standstill can be achieved by switching off the power supply contactor or by safe mechanical locking of moving parts.
- Secure vertical axes against falling or dropping after switching off the motor power by, for example:
- mechanically securing the vertical axes
- adding an external braking/ arrester/ clamping mechanism
- ensuring sufficient equilibration of the vertical axes

The standard equipment motor brake or an external brake controlled directly by the drive controller are not sufficient to guarantee personal safety!

- Disconnect electrical power to the equipment using a master switch and secure the switch against reconnection for:
- maintenance and repair work
- cleaning of equipment
- long periods of discontinued equipment use
- Prevent the operation of high-frequency, remote control and radio equipment near electronics circuits and supply leads. If the use of such equipment cannot be avoided, verify the system and the installation for possible malfunctions in all possible positions of normal use before initial startup. If necessary, perform a special electromagnetic compatibility (EMC) test on the installation.

3.8 Protection Against Magnetic and Electromagnetic Fields During Operation and Mounting

Magnetic and electromagnetic fields generated near current-carrying conductors and permanent magnets in motors represent a serious health hazard to persons with heart pacemakers, metal implants and hearing aids.



WARNING

Health hazard for persons with heart pacemakers, metal implants and hearing aids in proximity to electrical equipment!

- Persons with heart pacemakers, hearing aids and metal implants are not permitted to enter the following areas:
- Areas in which electrical equipment and parts are mounted, being operated or started up.
- Areas in which parts of motors with permanent magnets are being stored, operated, repaired or mounted.
- If it is necessary for a person with a heart pacemaker to enter such an area, then a doctor must be consulted prior to doing so. Heart pacemakers that are already implanted or will be implanted in the future, have a considerable variation in their electrical noise immunity. Therefore there are no rules with general validity.
- Persons with hearing aids, metal implants or metal pieces must consult a doctor before they enter the areas described above. Otherwise, health hazards will occur.

3.9 Protection Against Contact with Hot Parts



CAUTION

Housing surfaces could be extremely hot! Danger of injury! Danger of burns!

- Do not touch housing surfaces near sources of heat! Danger of burns!
- After switching the equipment off, wait at least ten (10) minutes to allow it to cool down before touching it.
- Do not touch hot parts of the equipment, such as housings with integrated heat sinks and resistors. Danger of burns!

3.10 Protection During Handling and Mounting

Under certain conditions, incorrect handling and mounting of parts and components may cause injuries.



CAUTION

Risk of injury by incorrect handling! Bodily harm caused by crushing, shearing, cutting and mechanical shock!

- Observe general installation and safety instructions with regard to handling and mounting.
- Use appropriate mounting and transport equipment.
- Take precautions to avoid pinching and crushing.
- Use only appropriate tools. If specified by the product documentation, special tools must be used.
- Use lifting devices and tools correctly and safely.
- For safe protection wear appropriate protective clothing, e.g. safety glasses, safety shoes and safety gloves.
- Never stand under suspended loads.
- Clean up liquids from the floor immediately to prevent slipping.

3.11 Battery Safety

Batteries contain reactive chemicals in a solid housing. Inappropriate handling may result in injuries or material damage.



CAUTION

Risk of injury by incorrect handling!

- Do not attempt to reactivate discharged batteries by heating or other methods (danger of explosion and cauterization).
- Never charge non-chargeable batteries (danger of leakage and explosion).
- Never throw batteries into a fire.
- Do not dismantle batteries.
- Do not damage electrical components installed in the equipment.



Be aware of environmental protection and disposal! The batteries contained in the product should be considered as hazardous material for land, air and sea transport in the sense of the legal requirements (danger of explosion). Dispose batteries separately from other waste. Observe the legal requirements in the country of installation.

3.12 Protection Against Pressurized Systems

Certain motors and drive controllers, corresponding to the information in the respective Project Planning Manual, must be provided with pressurized media, such as compressed air, hydraulic oil, cooling fluid and cooling lubricant supplied by external systems. Incorrect handling of the supply and connections of pressurized systems can lead to injuries or accidents. In these cases, improper handling of external supply systems, supply lines or connections can cause injuries or material damage.



CAUTION

Danger of injury by incorrect handling of pressurized systems!

- Do not attempt to disassemble, to open or to cut a pressurized system (danger of explosion).
- Observe the operation instructions of the respective manufacturer.
- Before disassembling pressurized systems, release pressure and drain off the fluid or gas.
- Use suitable protective clothing (for example safety glasses, safety shoes and safety gloves)
- Remove any fluid that has leaked out onto the floor immediately.



Environmental protection and disposal! The media used in the operation of the pressurized system equipment may not be environmentally compatible. Media that are damaging the environment must be disposed separately from normal waste. Observe the legal requirements in the country of installation.

4 Technical Data

4.1 Front Panel and Housing

Front Panel and Housing	
Housing	Steel Sheet, Galvanized
Front Panel	Aluminium, Varnished 209 mm x 159 mm x 3 mm (H x W x D) - (8.228" x 6.260" x 0.118")
Front Foil	Polyester Foil
Seal	Circumferential Rubber Seal on the Rear
Mounting Cutout	199 mm x 139 mm (H x W) - (7.835" x 5.472")
Mounting Depth	Approx. 58 mm (2.283") - (without Connector)
Degree of Protection	Front: IP54 Rear: IP20
Total Weight	Approx. 800 g

4.2 Keyboard

Keyboard	
Туре	Short-Stroke Keys with Tactile Feedback
Key Area (Embossment)	16 mm x 16 mm (0.630" x 0.630")
Actuator Travel	0.5 mm (0.020")
Activation Power	2 N to 3 N
Switching Cycles	Approx.1 Million
Number of Keys (Total)	36

4.3 Display

Display	
Туре	LCD-Module with LED Backlight
Resolution	120 x 32 Pixels
Pixel Color	Black
Background Color	Yellow-green

Display	
Reading Angle	90°
Default Contrast / Brightness Setting	By User Mode Switch
Contrast Setting	Temperature Compensated
LCD Lifetime	100.000 h
Half-Life Time of the Backlight	100.000 h
Lines (Font Normal)	4
Characters/Line (Font Normal)	20
Character Matrix (Font Normal)	6 x 8 Pixels
Character Matrix (Font Zoom)	12 x 16 Pixels
Pixel Size	1.14 mm x 0.95 mm (H x W) - (0.045" x 0.037")
Display Area	38 mm x 119 mm (H x W) - (1.496" x 4.685")

4.4 Electrical Data

Electrical Data	
Supply Voltage	24 V DC (SELV in Accordance with DIN EN 61131)
Residual Ripple	Maximum 10%
Minimum Voltage	19.2 V
Maximum Voltage	30.2 V
Power Consumption	<0.3 A
Peak Current	<0.5 A
Connected Load	~10 W
Fuse	Semiconductor Fuse, Self-resetting
Protection against Polarity Reversal	Integrated

4.5 Interfaces

Standard Interfaces		
Variable Baud Rates and Data Formats		
X3 SER1 TTY / 20 mA	According to CL 2 and DIN 66 348 T1 Transmission Length: 0 - 1000 m (3280.84 ft.), Twisted Pair, Shielded Electrically Isolated	
X3 SER1 RS485	According to DIN 66259-4 Transmission Length: 0 - 1200 m (3937.01 ft.), Twisted Pair, Shielded Electrically Isolated	
X3 SER1 RS232c / X3 SER2 RS232c	According to DIN 66259 T1, CCITT V.28 Transmission Length: 0 - 15 m (49.21 ft.), Layer-stranded, Shielded X3 SER1: Electrically Isolated X3 SER2: Not Electrically Isolated	

Field Bus Interfaces	
Variable Baud Rates and Data Formats	
X2.1 / X2.2 DeviceNet	According to ISO 11898 Electrically Isolated
X2.1 / X2.2 INTERBUS	Electrically Isolated
X2 PROFIBUS-DP	Electrically Isolated

4.6 Central Processing Unit and Memory

Central Unit		
Central Unit	Z84	
Clock Frequency	10 MHz	
Other Characteristics	Watchdog Timer, Real-Time Clock, Temperature Compensation of the Display, Battery Monitoring	

Memory		
Application Memory	256 KByte Flash	
RAM	128 KByte Static CMOS-RAM, Battery-Backed	

4.7 Connection System

Connection System
D-SUB Female and Male Connector Strips, 9-Pin and 25-Pin
Female and Male Connector Strips Phoenix COMBICON, 3-Pin

4.8 Ambient Conditions

Ambient Conditions				
Ambient Temper-	Operation	0 °C to 50 °C (32 °F to 122 °F)		
ature	Storage, Transport	- 20 °C to + 70 °C (- 4 °F to + 158 °F)		
Relative Humidity	Operation	10% to 95%, No Condensation		
	Storage, Transport	10% to 95%, No Condensation		
Application Area		Degree of Pollution 1, Over Voltage Category II		

4.9 Standards and Guidelines

Standards and Guidelines				
Interference Immunity	EN 61000-4-2 EN 61000-4-3 EN 61000-4-4 EN 61000-4-5 EN 61000-4-6			
Emitted Interference	EN 50081-1 Table A1 EN 55011 EN 55022			
Equipment Requirements	EN 61131			
Storage and Transport	EN 61131 Part 2			
Power Supply	EN 61131 Part 2			
Electromagnetic Compatibility	89/336/EWG (Including all Applicable Amendments)			
Degree of Protection	EN 60529			
Impact Load, Shocks	EN 60068 Part 2-27			
Sinusoidal Vibrations	EN 60068 Part 2-6			
Corrosion Protection	IEC 60068			

4.10 Compatibility Test

All Rexroth controls and drives are developed and tested according to the technological state-of-the-art.

As it is impossible to follow the continuing development of all materials (e.g. lubricants in machine tools) which may interact with our controls and drives, it cannot be completely ruled out that any reactions with the materials used by Bosch Rexroth might occur.

For this reason, before using the respective material a compatibility test has to be carried out for new lubricants, cleaning agents etc. and our housings/our housing materials.

5 Dimensions

5.1 Installation

TO TO	When installing the operator terminal, keep a minimum clearance of 30 mm (1.181") around the operator terminal to ensure adequate air circulation.
	When the operator terminal is installed horizontally, please note that additional sources of heat beneath the operator terminal may result in heat accumulation. Provide for sufficient heat dissipation! Comply with the allowable temperature range listed in the technical data for the use of the operator terminal!
	To maintain the specified degree of protection, make sure the seal is evenly seated on the installation surface and the hexagon nuts are tightened uniformly. Ensure that the maximum torque of 1.2 Nm is not exceeded.
	The operator terminal can be easily and quickly mounted from the rear of the operator terminal. This is particularly recommended for mounting in switchboards with a plate thickness of approx. 1 mm to 8 mm (approx. 0.039" to 0.315").

- 1. Insert the operator terminal from the front through the mounting cut-
- 2. Fasten the operator terminal using hexagon nuts.

5.1.1 Front Panel Dimensions

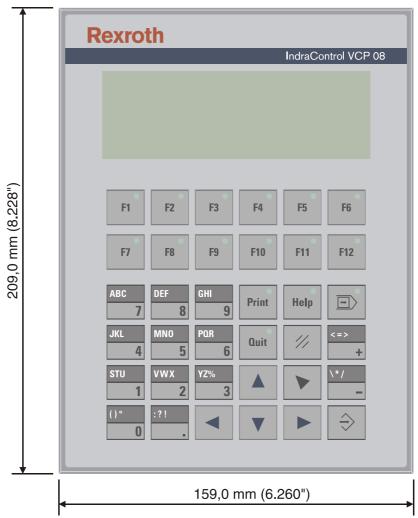


Fig. 5-1: Front panel dimensions

5.1.2 Mounting Cutout

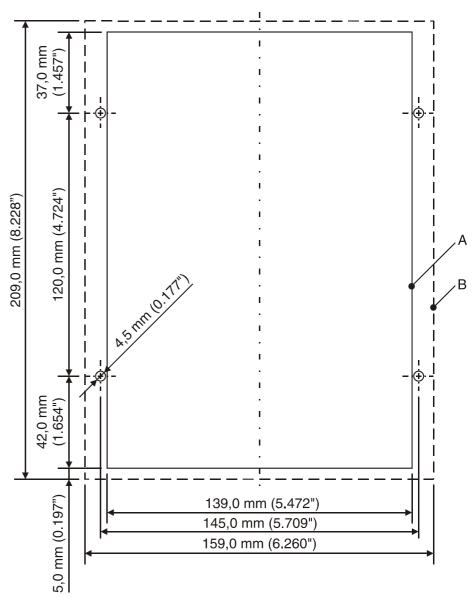


Fig. 5-2: Mounting cutout

- **A** Mounting Cutout
- **B** Front Panel

5.1.3 Side View, Mounting Depth

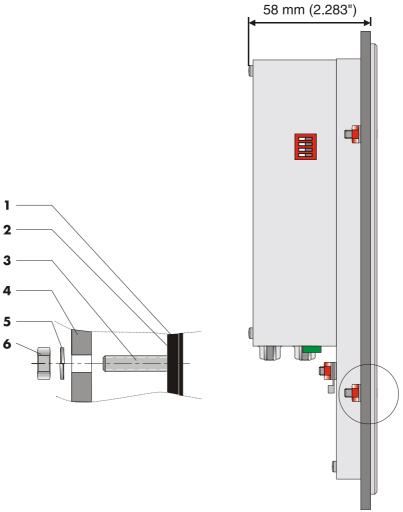


Fig. 5-3: Side view and mounting depth of standard and field bus device

- 1 Front Panel
- 2 Circumferential Seal
- 3 Press-in Threaded Bolt M4 x 18 mm (0.709")
- 4 Mounting Surface Thickness 1 mm to 8 mm (0.039" to 0.315")
- 5 Spring Lock Washer B4 DIN 127 Form B (not supplied)
- 6 Nut M4 DIN 934 (not supplied)

6 Display and Operating Components

6.1 Display



Danger of intoxication!

If the display is damaged, avoid touching, swallowing or breathing in the liquids or gases which may leak out.



Danger of corrosion!

If the display is damaged, avoid touching, swallowing or breathing in the liquids or gases which may leak out.

6.1.1 Setting the Contrast

To define the contrast setting, use the programming software to set up the system variable **LcdContrast** in any mask.



To do so, follow the instructions listed in the programming software's help topic "How do I specify the contrast / brightness setting for the operating device".

In the programming software, enter the following values as lower and upper limits for the representation type.

System Variable	Lower Limit	Upper Limit	Default Setting
LcdContrast	- 25	+ 70	+ 25

Fig. 6-1: Values for the representation type



If you do not configure the system variable **LcdContrast**, the default setting is used when the device is initialized.

If you did set-up the system variable, you can set the contrast as follows. Open the mask where you set up the system variable and:

- Press the data release key if the data release is not automatically active.
- 2. Enter a new value for the contrast. To do so, use the keys 0-9 or plus and minus.
- 3. Confirm with Enter.
- 4. Finally press the data release key.

The new contrast setting becomes effective immediately after the Enter key is pressed. If necessary, repeat the steps two and three until you are satisfied with the contrast.

6.1.2 Default Contrast Setting

If the contrast setting is such that it is no longer possible to read the masks, you can use the user mode switch to reset the contrast to the default value.



For the table with the switch positions of the user mode switch, see chapter "User Mode Switch".



The switch position for the default contrast is identical with the "Activate download via hardware". The contrast is reset before a corresponding message is displayed. The warning will be displayed in a legible manner.

To restore the default contrast:

- 1. Switch the device off.
- 2. Set the switches S1 and S4 of the user mode switch to ON.
- 3. Switch the device on again.
- 4. When the warning appears, switch the device off again.
- 5. Set switch S4 to OFF.
- 6. Then switch the device on again.

The application will not be lost.

6.1.3 Character Attributes

The following character attributes can be displayed on the device:

- Normal
- Flashing

6.1.4 Fonts

You are able to use the font "Normal" and the font "Zoom" or create and use your own character sets.

6.2 Keyboard

The keys are positioned under an environmental-proof polyester foil. You project the operating principle of the keys in the programming software.

6.2.1 Edit Keys

To activate the edit mode, you must press the data release key at first. After the status LED "data release" lights up an input with the edit keys is possible.



The key $\bf 0$ and $\bf ()^\circ$ is used for changing data in the editor. The (,) and $^\circ$ characters can be entered when configuring the **Shift** or **ShiftCase** system variables.



The key **1 and STU** is used for changing data in the editor. The characters S, T and U can be entered when configuring the **Shift** or **ShiftCase** system variables.



The key **2 and VWX** is used for changing data in the editor. The characters V, W and X can be entered when configuring the **Shift** or **Shift-Case** system variables.



The key **3 and YZ%** is used for changing data in the editor. The characters Y, Z and % can be entered when configuring the **Shift** or **ShiftCase** system variables.



The key **4 and JKL** is used for changing data in the editor. The characters J, K and L can be entered when configuring the **Shift** or **ShiftCase** system variables.



The key **5 and MNO** is used for changing data in the editor. The characters M, N and O can be entered when configuring the **Shift** or **Shift-Case** system variables.



The key **6 and PQR** is used for changing data in the editor. The characters P, Q and R can be entered when configuring the **Shift** or **ShiftCase** system variables.



The key **7 and ABC** is used for changing data in the editor. The characters A, B and C can be entered when configuring the **Shift** or **ShiftCase** system variables.



The key **8 and DEF** is used for changing data in the editor. The characters D, E and F can be entered when configuring the **Shift** or **ShiftCase** system variables.



The key **9 and GHI** is used for changing data in the editor. The characters G, H and I can be entered when configuring the **Shift** or **ShiftCase** system variables.



The key **Decimal point and :?!** is used for changing data in the editor. The characters :, ? and ! can be entered when configuring the **Shift** or **ShiftCase** system variables.



The key **Plus and <=>** is used for changing data in the editor. The characters <, = and > can be entered when configuring the **Shift** or **Shift-Case** system variables.



The key **Minus and */** is used for changing data in the editor. The characters \, * and / can be entered when configuring the **Shift** or **ShiftCase** system variables.

6.2.2 Navigation Keys



The key **Cursor left** can be programmed to directly select adjacent nodes and I/O masks. In the editor it moves the cursor one character to the left (character selection).



The key **Cursor right** can be programmed to directly select adjacent nodes and I/O masks. In the editor it moves the cursor one character to the right (character selection).



The key **Cursor down** can be programmed to directly select adjacent nodes and I/O masks. In the editor it moves the cursor down one variable (variable selection).



The key **Cursor up** can be programmed to directly select adjacent nodes and I/O masks. In the editor it moves the cursor up one variable (variable selection).



The key **Cursor home** can be programmed to directly select higher-level nodes and I/O masks. In the editor it returns the cursor to the first input variable position.

6.2.3 Special Keys



The key **Help** always shows the current help text (online help). A flashing help LED indicates that theere is a message. The system message is always shown in plain text.



The key **Print** can be used as a soft key to activate various print jobs.



The key **Acknowledge** is used as acknowledge key for the message system.



The key **Enter** is used to end the data entry. Pressing it during the start mask opens the setup mask.



The key **Data release** changes from the menu to the editor. The integrated LED is lit during edit mode. Pressing data release in edit mode exits the editor.



The key **Delete** deletes the character beneath the cursor in the editor. Removes the selected messages from the data memory.

6.2.4 Function Keys



The function of the function keys can be freely assigned (with soft key functions). The function keys can used either as direct keys for menu control of for triggering a function in the control system.

6.2.4.1 Slide-in Identification Strips for the Function Keys

The identifications strips can be replaced when the operating device is removed. Inserting the strip from the rear side of the front plate does not influence the specified seal of the operator terminal. A set of identification strips is supplied with the operator terminal.

For the labeling use:

Single pieces, prototypes Label with a water-resistant pen
Small series Copying foil with laser print

Large series Customer-specific labeled identification

strips

The set consists of

- one identification strip, abeled F1 to F12 and
- · one unlabeled identification strip.

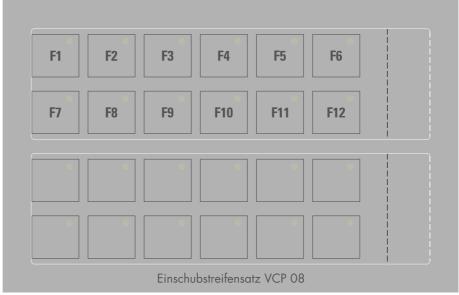


Fig. 6-2: Identification strip set for VCP 08

Display and Operating Components



Fig. 6-3: Position of the identification strip

Display and Operating Components

6.2.5 User Mode Switch

The user mode switch is located on the rear of the small operator terminal.



The switch positions for ON or OFF are printed onto the user mode switch.

S1	S2	S3	S4	Operating Mode
I	Х	-	_	Standard mode with PLC (default upon delivery)
ı	Х	I	_	Standard mode without PLC
_	I	_	_	Transparent mode with start- and stop code of the keys
_	_	_	Ι	Transparent mode without stop code of the keys
I	_	_	I	Activate download (erases the application memory) and default contrast / brightness setting
I	_	I	I	Activate upload

Fig. 6-4: User mode switch

Legend for table:

I = Switch ON

-= Switch OFF

X = Any switch position

7 Interfaces

The device can either be supplied as a standard device or field bus device.

The universal interface X3 combines several interface standards in one connector. The connector is divided into two channels. The communication channel (SER1) is operated separately from the channel for the upload/download/logging printer/scanner (SER2).

For the communication channel (SER1), the protocol-specific use only allows one of the three interface standards to be used.

Depending on the device variant, several interfaces are available to you:

Type code		Available interfaces					
	RS232c (X3-SER2)	TTY / 20mA, RS485, RS232c (X3-SER1)	DeviceNet	INTERBUS	PROFIBUS DP		
VCPxx.xxxx-xxxRS-xx-xx	Х	Х	-	-	-		
VCPxx.xxxx-xxxDN-xx-xx	Х	-	Χ	-	-		
VCPxx.xxxx-xxxIB-xx-xx	Х	-	-	Х	-		
VCPxx.xxxx-xxxPB-xx-xx	Х	-	-	-	Х		

Fig. 7-1: Device variants

7.1 Standard Interfaces

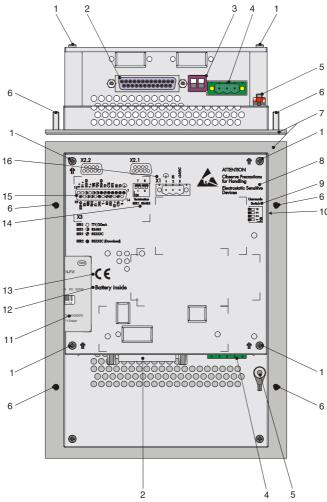


Fig. 7-2: Rear view of standard device

- 1. Fastening Screws
- 2. Female Connector X3 (TTY/RS485/RS232c)
- 3. Termination Switch (X3-SER1 RS485)
- 4. Connector X1 (Supply Voltage)
- 5. Threaded Bolt for Protective Grounding
- 6. Mounting Bolt
- 7. Front Panel
- 8. Warning
- 9. Assignment for User Mode Switch
- 10. User Mode Switch on the Side
- 11. Nameplate
- 12. Battery-related information
- 13. CE Mark
- 14. Assignment for Termination Switch (X3-SER1 RS485)
- 15. Assignment Connector X3 (TTY/RS485/RS232c)
- 16. Assignment Connector X1 (Supply Voltage)

7.1.1 TTY / 20 mA Current Loop (X3-SER1)

Depending on the wiring, it is possible to connect the interface either as an active or passive current loop. The transmit line and the receive line are each provided with a separate 20 mA power source. The compliance voltage is approx. 24 VDC.

The 20 mA power should be supplied by the transmitter unit. This decreases crosstalk on the signal lines considerably.

In idle state (signal logic 1), a 20 mA current loop can be measured in the cable.

Signal Logic 1 Current Flow 20 mA
Signal Logic 0 Current Flow Interrupted

7.1.1.1 Pin Assignment

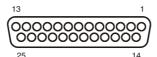


Fig. 7-3: 25 pin D-SUB female connector strip

Connector in the small operator terminal: 25-pin D-SUB female connector strip

Pin	Designation	Function
10	T+	Transmitted Data, Positive Polarity
13	R+	Received Data, Positive Polarity
14	R-	Received Data, Negative Polarity
19	T-	Transmitted Data, Negative Polarity

Fig. 7-4: Pin assignment TTY / 20 mA, passive

Pin	Designation	Function
10	T+	Transmitted Data, Positive Polarity
12	S1+	Power Source 1, Positive Polarity
13	R+	Received Data, Positive Polarity
14	R-	Received Data, Negative Polarity
16	S2+	Power Source 2, Positive Polarity
19	T-	Transmitted Data, Negative Polarity
21	S1-	Current Sink 1, Negative Polarity
24	S2-	Current Sink 2, Negative Polarity

Fig. 7-5: Pin assignment TTY / 20 mA, active



The D-SUB connector strips must be shielded sufficiently. See chapter "Shielding D-SUB Connectors" on page 7-21.

7.1.1.2 Termination



When channel SER1 is operated as a current loop, the termination for the RS485 must be OFF.

7.1.2 RS485 (X3-SER1)

The interface is suitable for point-to-point and for multi-point connections.

The wires belonging together are marked with "A" and "B". Some descriptions refer to the pins with "+" and "-", where A = + and B = -.

Signal Logic 1 $U_A - U_B \le -0.3 \text{ V i.e.}$ ($U_A < U_B$) Signal Logic 0 $U_A - U_B \ge +0.3 \text{ V i.e.}$ ($U_A > U_B$)

7.1.2.1 Pin Assignment

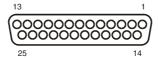


Fig. 7-6: 25 pin D-SUB female connector strip

Connector in the small operator terminal: 25-pin D-SUB female connector strip

Pin	Designation	Function
8	T(A)	Transmitted data (+)
9	T(B)	Transmitted data (-)
11	SGND	Signal Ground
22	R(A)	Received data (+)
23	R(B)	Received data (-)

Fig. 7-7: Pin assignment RS485



The D-SUB connector strips must be shielded sufficiently. See chapter "Shielding D-SUB Connectors" on page 7-21.

7.1.2.2 Termination

For point-to-point connections, always activate the termination. For multi-point connections, only activate the termination at the cable end.

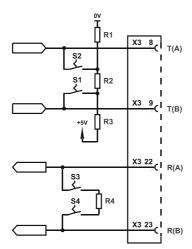


Fig. 7-8: Block diagram termination RS485

Designation	Value
R1, R3	510 Ohm
R2	150 Ohm
R4	120 Ohm

Fig. 7-9: Resistance values termination RS485



The switch positions for ON or OFF are printed onto the termination switch. Only the specified switch positions are permitted.

S1	S2	S3	S4	Function
Transmitter		Receiver		
I	I	ı	I	Termination is ON
_	_	_	_	Termination is OFF

Fig. 7-10: Termination switch

Legend for table:

I = Switch ON

- = Switch OFF

7.1.3 RS232c (X3-SER1)

The interface is suitable to establish a point-to-point connection.

7.1.3.1 Pin Assignment



Fig. 7-11: 25 pin D-SUB female connector strip

Connector in the small operator terminal: 25-pin D-SUB female connector strip

Pin	Designation	Function
6	TD	Transmitted Data
15	CTS	Clear to Send
17	RTS	Request to Send
18	RD	Received Data
25	SGND	Signal Ground

Fig. 7-12: Pin assignment RS232c



The D-SUB connector strips must be shielded sufficiently. See chapter "Shielding D-SUB Connectors" on page 7-21.

7.1.3.2 Termination



For the operation of channel SER1 as a RS232, the termination for the RS485 must be OFF.

7.1.4 RS232c (X3-SER2)

The interface is only designed to be used for downloads, uploads, a scanner or a logging printer because the interface is not electrically isolated.

7.1.4.1 Pin Assignment

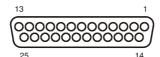


Fig. 7-13: 25-pin D-SUB female connector strip

Connector in the small operator terminal: 25-pin D-SUB female connector strip

Pin	Designation	Function
1	Ē	Low-Noise Ground
2	TD	Transmitted Data
3	RD	Received Data
4	RTS	Request to Send
5	CTS	Clear to Send
7	SGND	Signal Ground
20	DTR	Data Transfer Request

Fig. 7-14: Pin assignment of the RS232c interface



The D-SUB connector strips must be shielded sufficiently. See chapter "Shielding D-SUB Connectors" on page 7-21.

7.2 Field Bus Interfaces

7.2.1 DeviceNet (X2.1 / X2.2)

The device can be integrated into the DeviceNet bus using the interfaces available for DeviceNet connections.

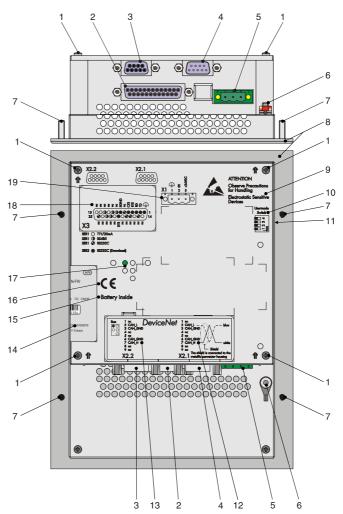


Fig. 7-15: Rear view DeviceNet

- 1. Fastening Screws
- 2. Female Connector X3 (SER2 RS232c)
- 3. Female Connector X2.2 (DeviceNet)
- 4. Male Connector X2.1 (DeviceNet)
- 5. Connector X1 (Supply Voltage)
- 6. Threaded Bolt for Protective Grounding
- 7. Mounting Bolt
- 8. Front Panel
- 9. Warning
- 10. Assignment for User Mode Switch
- 11. User Mode Switch on the Side
- 12. Assignment Male Connector X2.1 (DeviceNet)
- 13. Assignment Female Connector X2.2 (DeviceNet)
- 14. Nameplate
- 15. Battery-related information
- 16. CE Mark
- 17. Diagnostic LED
- 18. Assignment Female Connector X3 (SER2 RS232c)
- 19. Assignment Connector X1 (Supply Voltage)

7.2.1.1 Pin Assignment

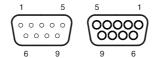


Fig. 7-16: 9-pin D-SUB male and female connector strip

Connector in the small operator terminal: 9-pin D-SUB male and female connector strip (assignment for male and female connector strip is the same).

Pin	Designation	Function
1	nc	Not Connected
2	CAN_L	CAN_L Bus Line (Dominant LOW)
3	CAN_GND	CAN Ground
4	nc	Not Connected
5	nc	Not Connected
6	CAN_GND	CAN Ground
7	CAN_H	CAN_H Bus Line (Dominant HIGH)
8	nc	Not Connected
9	nc	Not Connected

Fig. 7-17: Pin assignment DeviceNet

All signal lines are looped through from X2.1 to X2.2. The connecting cables should be connected to every pin, including the reserved pins. In this way, the cables can still be used in case of future bus specification extensions.



The D-SUB connector strips must be shielded sufficiently. See chapter "Shielding D-SUB Connectors" on page 7-21.

7.2.1.2 Cable



A DeviceNet-certified cable must be used.

Cable Loop resistance type			Capacitance per unit length
2 x 1.1 mm	< 22.6 Ohm/km	120 Ohm	< 39.4 pf/m
2 x 0.6 mm	< 91.8 Ohm/km	120 Ohm	< 39.4 pf/m

Fig. 7-18: Data line DeviceNet

The maximum length allowed for spur lines connected to the bus cable is 6 meters. The overall length of the bus cable including all spur lines is not to exceed the maximum length listed in the table below.

The maximum cable length depends on the baud rate and the cable type used.

Baud rate	Cable type	Cable length
125 kBit/s	2 x 1.1 mm	500 m
	2 x 0.6 mm	100 m
250 kBit/s	2 x 1.1 mm	250 m
	2 x 0.6 mm	100 m
500 kBit/s	2 x 1.1 mm	100 m
	2 x 0.6 mm	100 m

Fig. 7-19: Baud rate DeviceNet

7.2.1.3 Termination

Terminate the DeviceNet bus at both ends by terminating resistors (120 Ohm).

7.2.1.4 Diagnostics

A diagnostic LED is located at the rear of the small operator terminal. The LED shows the states of the bus system.



Fig. 7-20: Arrangement of the DeviceNet diagnostic LED

The diagnostic LED at the small operator terminal has the following functions:

Color	State	Function	
Green	Off	Terminal Disconnected from Bus	
Green	On	Communication Active	
Green	Flashing	Sporadic Bus Error	

Fig. 7-21: Function of the DeviceNet diagnostic LED

7.2.2 INTERBUS (X2.1 / X2.2)

The device can be integrated into the INTERBUS using the interfaces available for INTERBUS connections.

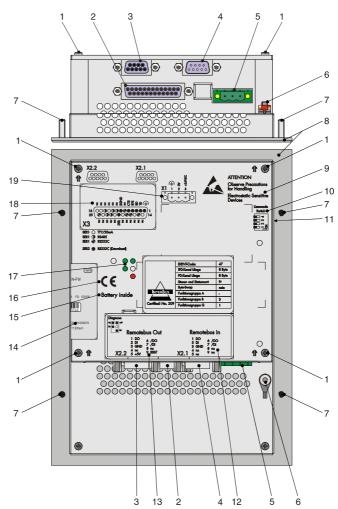


Fig. 7-22: Rear view INTERBUS

- 1. Fastening Screws
- 2. Female Connector X3 (SER2 RS232c)
- 3. Female Connector X2.2 (Remotebus out)
- 4. Male Connector X2.1 (Remotebus in)
- 5. Connector X1 (Supply Voltage)
- 6. Threaded Bolt for Protective Grounding
- 7. Mounting Bolt
- 8. Front Panel
- 9. Warning
- 10. Assignment for User Mode Switch
- 11. User Mode Switch on the Side
- 12. Assignment Male Connector X2.1 (Remotebus in)
- 13. Assignment Female Connector X2.2 (Remotebus out)
- 14. Nameplate
- 15. Battery-related information
- 16. CE Mark
- 17. Diagnostic LEDs
- 18. Assignment Female Connector X3 (SER2 RS232c)
- 19. Assignment Connector X1 (Supply Voltage)

7.2.2.1 Pin Assignment

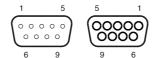


Fig. 7-23: 9-pin D-SUB male and female connector strip

Connector in the small operator terminal: 9-pin D-SUB male connector strip for remote bus in.

Pin	Designation	Function	
1	DO	Data Output	
2	DI	Data Input	
3	GND	Ground	
4	nc	Not Connected	
5	nc	Not Connected	
6	/DO	Data Output, Inverted	
7	/DI	Data Input, Inverted	
8	nc	Not Connected	
9	nc	Not Connected	

Fig. 7-24: Pin assignment INTERBUS

Connector in the small operator terminal: 9-pin D-SUB female connector strip for remote bus out.

Pin	Designation	Function	
1	DO	Data Output	
2	DI	Data Input	
3	GND	Ground	
4	nc	Not Connected	
5	+5 V	Power Supply +5 VDC	
6	/DO	Data Output, Inverted	
7	/DI	Data Input, Inverted	
8	nc	Not Connected	
9	RBST	Remote Bus Status	

Fig. 7-25: Pin assignment INTERBUS



The D-SUB connector strips must be shielded sufficiently. See chapter "Shielding D-SUB Connectors" on page 7-21.

7.2.2.2 Cable



A shielded twisted-pair cable (cable type LiYCY-TP) must be used. The maximum cable length depends on its use within the INTERBUS topology.

7.2.2.3 Diagnostics

The diagnostic LEDs are located at the rear of the small operator terminal. The LEDs show the states of the bus system.



Fig. 7-26: Arrangement of the INTERBUS diagnostic LEDs

The diagnostic LEDs at the small operator terminal has the following functions:

Designation	Color	State	Function
RC	Green	On	Remote Bus Check
+5 V	Green	On	Supply Voltage OK
		Off	No Supply Voltage
ВА	Green	On	Bus Active
		Off	Bus Not Active
RD	Red	On	Remote Bus Inactive

Fig. 7-27: Functions of the INTERBUS diagnostic LEDs

7.2.3 PROFIBUS DP (X2)

The interface for PROFIBUS DP connections is available to integrate the device into a PROFIBUS DP structure.

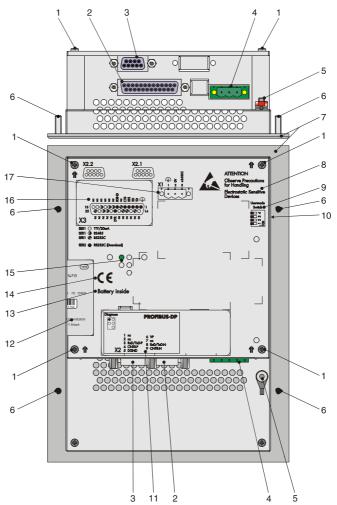


Fig. 7-28: Rear view PROFIBUS DP

- 1. Fastening Screws
- 2. Female Connector X3 (SER2 RS232c)
- 3. Female Connector X2 (PROFIBUS DP)
- 4. Connector X1 (Supply Voltage)
- 5. Threaded Bolt for Protective Grounding
- 6. Mounting Bolt
- 7. Front Panel
- 8. Warning
- 9. Assignment for User Mode Switch
- 10. User Mode Switch on the Side
- 11. Assignment Female Connector X2 (PROFIBUS DP)
- 12. Nameplate
- 13. Battery-related information
- 14. CE Mark
- 15. Diagnostic LED
- 16. Assignment Female Connector X3 (SER2 RS232c)
- 17. Assignment Connector X1 (Supply Voltage)

7.2.3.1 Pin Assignment



Fig. 7-29: 9-pin D-SUB female connector strip

Connector in the small operator terminal: 9-pin D-SUB female connector strip

Pin	Designation	Function		
1	nc	Not Connected		
2	nc	Not Connected		
3	RxD/TxD-P	Received Data / Transmitted Data Plus		
4	CNTR-P	Repeater Control Signal Plus		
5	DGND	Data Transmission Potential		
6	VP	Supply Voltage of Terminators Plus		
7	nc	Not Connected		
8	RxD/TxD-N	Received Data / Transmitted Data Minus		
9	CNTR-N	Repeater Control Signal Minus		

Fig. 7-30: Pin assignment PROFIBUS DP



The D-SUB connector strips must be shielded sufficiently. See chapter "Shielding D-SUB Connectors" on page 7-21.

7.2.3.2 Cable



Any PROFIBUS DP-approved cables specified in the EN 50170 as cable type A can be used.

Impedance 136 to 165 Ohm

Capacity < 30 pf/m
Loop resistance 110 Ohm/km

Wire gauge 0.64 mm

The maximum cable length depends on the baud rate (DIN EN 19245 Part 3).

Baud Rate	Cable Length
187.5 kbits/s	1000 m
500 kbits/s	400 m
1500 kbits/s	200 m
3000 to 12000 kbits/s	100 m

Fig. 7-31: Baud rate PROFIBUS DP

7.2.3.3 Termination

Terminate the PROFIBUS at both ends by terminating resistors. If you are using special PROFIBUS connectors, these resistors are usually integrated into the connector and can be connected.

7.2.3.4 Diagnostics

A diagnostic LED is located on the rear of the small operator terminal. The LED shows a state of the bus system.



Fig. 7-32: Arrangement of the PROFIBUS DP diagnostic LED

The diagnostic LED on the small operator terminal has the following function:

Color	State	Function
Green	On	Communication active

Fig. 7-33: Function of the PROFIBUS-DP diagnostic LED

7.3 Shielding D-SUB Connectors

You must shield D-SUB connectors as follows:

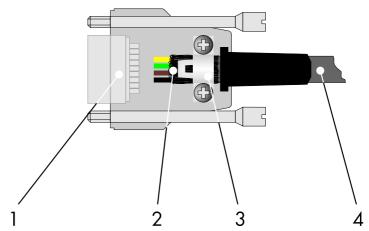


Fig. 7-34: Shielding D-SUB connectors

- 1 D-SUB connector
- 2 Shield
- 3 Cable clip
- 4 Cable

The shield must be folded back into a flat position over the cable sheath.

When fastening the cable with the cable clip, as much of the shielding as possible must be in contact with the housing and sufficient strain relieve must be ensured.

8 Maintenance and Installation

8.1 General Information

VCP-type operator terminals are maintenance-free. A few parts are subject to wear and must be replaced after a certain number of operating hours.

8.2 Exchange of Hardware Components



CAUTION

Maintenance work in the device is only permissible by skilled stuff! If hardware components have to be exchanged, please contact the Bosch Rexroth Service or ensure that only skilled stuff changes the respective components.

8.3 Data Backup



CAUTION

The Bosch Rexroth AG is not liable for possible data loss and the damages resulting from this!

The customer himself is responsible for the backup of customer-specific data and must provide this data in case of service.

8.4 Unpacking the Device

Unpack all parts carefully and check the contents for any visible transport damage. Also check whether the shipment matches the specifications on your delivery note.

If you notice transport damages or discrepancies, please contact our sales department immediately.

8.5 Identification

You can identify the small operator terminal by the nameplate on the rear.

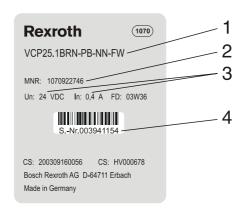


Fig. 8-1: Nameplate (example)

- 1 Ordering name / Short type designation
- 2 Part number
- 3 Voltage and power specification
- 4 Serial number

Depending on the size of the display, you will be able to read various types of information as the operating device is initialized: clock frequency, application memory size, current firmware version, programming software version, project name, time, date, number of compilation runs and a random number.



Because the initialization mask is visible only for a few seconds there is a possibility to represent this mask for a longer time period.

- 1. Hold down an arbitrary key at the operator terminal to generate an error message.
- 2. Read the firmware version now.
- 3. Release the key to complete the initialization procedure of the operator terminal.

8.6 Connecting

8.6.1 Supply Voltage 24 V

The supply voltage is supplied via connector X1.

The device has reverse polarity protection. In case of wrong polarity, the device will not operate.

This is a protection class I device. For safe operation, safety extra-low voltage (SELV) in accordance with DIN EN 61131 must be used for the supply voltage.

Connector in the terminal: 3-pin connector Phoenix COMBICON MSTBV 2,5/3-GF.

Pin	Designation	Function
1	Ē	Low-Noise Ground
2	0 V	Supply Voltage 0 V
3	24 VDC	Supply Voltage 24 VDC

Fig. 8-2: Pin assignment supply voltage

A suitable female connector strip of the type Phoenix COMBICON MSTB 2,5/3-STF is supplied.



A cable with finely stranded wires with a minimum cross-section of 0.75 mm² (18 AWG) and a maximum cross-section of 2.5 mm² (14 AWG) must be used for the supply voltage.



WARNING

Hazardous voltages can exist inside electrical installations that can pose a danger to humans. Coming in contact with live parts may result in electric shock!

Use the following procedure to connect the device to the supply voltage:

1. Remove approx. 30 mm (1.181") off the outer cable sheath and approx. 5 mm (0.197") off the wires.

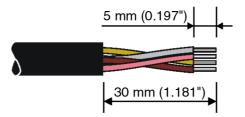


Fig. 8-3: Preparing the cable

2. Fit the wires with wire end ferrules and connect the wires to the connector.

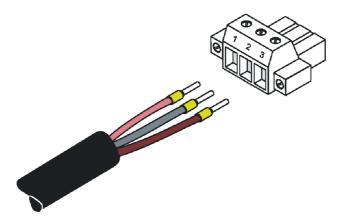


Fig. 8-4: Connecting the female connector strip



If shielded connecting cables are used in the supply voltage area, the shield should be connected to pin 1.

3. Plug the female connector strip onto connector X1.A.

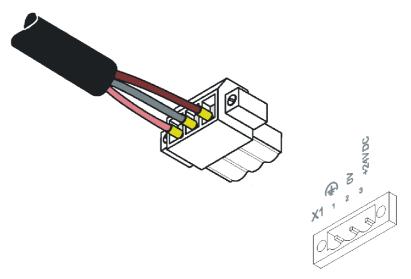


Fig. 8-5: Female connector strip is plugged on

4. Secure the female connector strip in place with a screw-type locking to prevent it from slipping out.



A separate conductor must always be provided for the protective grounding at the threaded bolt. The conductor must have a minimum cross-section of 1.5 mm² (16 AWG) and must be kept as short as possible. Complying with this will increase operating safety.

8.7 Front Panel

You should use a damp cloth only to remove any dirt from the panel.

8.8 Fuse



The semiconductor fuse cannot be replaced!

A semiconductor fuse is used to protect the device. Once the fuse has been tripped, the device must be disconnected from the supply voltage to allow the semiconductor fuse to regenerate. At an ambient temperature of 20 $^{\circ}$ C (68 $^{\circ}$ F), the regeneration takes approximately 20 seconds. The higher the ambient temperature, the longer the regeneration takes.

8.9 Battery

The built-in battery preserves the data in the CMOS-RAM and supplies the real-time clock. The minimum battery life is 5 years, even under unfavorable operating conditions. When the battery runs down, the message "Change battery" is generated automatically.

We recommend you change the battery approximately every 4 years as part of the regular maintenance work. A pre-assembled battery including connector can be obtained directly from Bosch Rexroth.

If the "Change battery" message is detected too late, e.g. the real-time clock stopped or shows the wrong date, data in the CMOS-RAM may have already been lost. For this reason, after changing a battery, always check data such as passwords that can be modified, parameters in the system variables, recipe data sets and entries in the message system.

8.9.1 Changing the Battery

To ensure that the data in the CMOS-RAM and the time are preserved, it is possible to change the battery under operating voltage. Observe the safety notes!

- 1. Remove the threaded bolts of the interfaces.
- 2. Remove the screws on the rear panel of the device and lift off the housing.
- 3. Remove the cable fastener securing the battery.
- 4. Disconnect the connector from the battery and remove the dead battery.
- 5. Plug in the cable of the new battery.
- 6. Use a cable fastener to attach the new battery to the housing.
- 7. Place the rear panel back onto the device.
- 8. Carefully tighten the screws of the rear panel and then the threaded bolts of the interfaces.

8.9.2 Battery Disposal



To prevent short circuitry in the collection boxes, insulate the poles of each battery with insulation tape or put each single battery into a plastic bag.

You must always return old batteries to a dealer or to a returns depot set up for this purpose by the public waste disposal body or a licensed battery dealer for recycling. Only dispose of dead batteries in public or commercial collection boxes. The battery is drained when the message "Change battery" appears on the display of the device. Ordering Information

9 Ordering Information

9.1 Type Code

The small operator terminals VCP 08 are available in different variants. Type code:

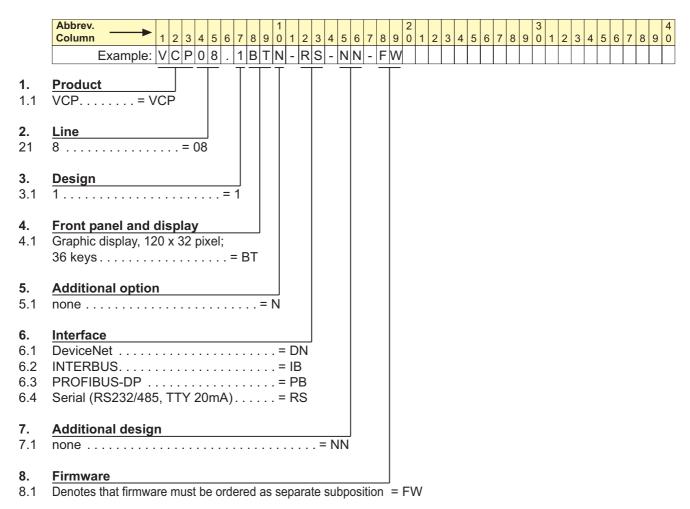


Fig. 9-1: Type code of the VCP 08

Ordering Information

9.2 Accessories

Ordering Designation	Material Number	Description
-	1070917922	Battery
IKB0053	R911305271	Download cable
IKB0033	R911291808	PROFIBUS cable
IKB0051	R911305089	Serial cable RS422
IKB0052	R911305090	Serial cable RS232

Fig. 9-2: Accessories

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12 Service & Support

12.1 Helpdesk

Unser Kundendienst-Helpdesk im Hauptwerk Lohr am Main steht Ihnen mit Rat und Tat zur Seite. Sie erreichen uns

telefonisch - by phone:
 über Service Call Entry Center
 via Service Call Entry Center

per Fax - by fax:

Our service helpdesk at our headquarters in Lohr am Main, Germany can assist you in all kinds of inquiries. Contact us

49 (0) 9352 40 50 60Mo-Fr 07:00-18:00

Mo-Fr 7:00 am - 6:00 pm

+49 (0) 9352 40 49 41

- per e-Mail - by e-mail: service.svc@boschrexroth.de

12.2 Service-Hotline

Außerhalb der Helpdesk-Zeiten ist der Service direkt ansprechbar unter

After helpdesk hours, contact our service department directly at

+49 (0) 171 333 88 26

oder - or +49 (0) 172 660 04 06

12.3 Internet

Unter	www.bos	chrex	roth.co	m f	inden	Sie
ergänz	ende Hinwe	ise zu	Service,	Repa	aratur	und
Trainin	g sowie die	aktuel	l en Adre	ssen	*) uns	erer
auf de	n folgenden	Seiten	aufgefül	hrten	Vertri	ebs-
und Se	rvicebüros.					

Verkaufsniederlassungen
Niederlassungen mit Kundendienst

Außerhalb Deutschlands nehmen Sie bitte zuerst Kontakt mit unserem für Sie nächstgelegenen Ansprechpartner auf.

*) Die Angaben in der vorliegenden Dokumentation k\u00f6nnen seit Drucklegung \u00fcberholt sein. At **www.boschrexroth.com** you may find additional notes about service, repairs and training in the Internet, as well as the **actual** addresses *) of our sales- and service facilities figuring on the following pages.

sales agencies
offices providing service

Please contact our sales / service office in your area first.

*) Data in the present documentation may have become obsolete since printing.

12.4 Vor der Kontaktaufnahme... - Before contacting us...

Wir können Ihnen schnell und effizient helfen wenn Sie folgende Informationen bereithalten:

- detaillierte Beschreibung der Störung und der Umstände.
- Angaben auf dem Typenschild der betreffenden Produkte, insbesondere Typenschlüssel und Seriennummern.
- 3. Tel.-/Faxnummern und e-Mail-Adresse, unter denen Sie für Rückfragen zu erreichen sind.

For quick and efficient help, please have the following information ready:

- Detailed description of the failure and circumstances.
- Information on the type plate of the affected products, especially type codes and serial numbers.
- 3. Your phone/fax numbers and email address, so we can contact you in case of questions.

12.5 Kundenbetreuungsstellen - Sales & Service Facilities

12.5.1 Deutschland - Germany

vom Ausland:

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12.5.4 Afrika, Asien, Australien (inkl. Pazifischer Raum) - Africa, Asia, Australia (incl. Pacific Rim)

Australia - Australien	Australia - Australien	China	China Shanghai Bosch Rexroth Hydraulics & Automation Ltd. 4/f, Marine Tower No.1, Pudong Avenue Shanghai 200120 - P.R.China Tel: +86 21 68 86 15 88 Fax: +86 21 58 40 65 77	
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Tel.: +86 10 65 05 03 80 Fax: +86 10 65 05 03 79	Tel.: +86 20 8755-0030 +86 20 8755-0011 Fax: +86 20 8755-2387	Tel.: +86 411 46 78 930 Fax: +86 411 46 78 932	Tel.: +86 21 6352 8848 Fax: +86 21 6351 3138	
Hongkong	India - Indien	India - Indien	India - Indien	
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Indonesia - Indonesien	Japan	Japan	Korea	
PT. Bosch Rexroth Building # 202, Cilandak Commercial Estate Jl. Cilandak KKO, Jakarta 12560 Tel.: +62 21 7891169 (5 lines) Fax: +62 21 7891170 - 71 rudy.karimun@boschrexroth.co.id	Bosch Rexroth Automation Corp. Service Center Japan Yutakagaoka 1810, Meito-ku, NAGOYA 465-0035, Japan Tel.: +81 52 777 88 41 +81 52 777 88 53 +81 52 777 88 79 Fax: +81 52 777 89 01	Bosch Rexroth Automation Corp. Electric Drives & Controls 2F, I.R. Building Nakamachidai 4-26-44, Tsuzuki-ku YOKOHAMA 224-0041, Japan Tel.: +81 45 942 72 10 Fax: +81 45 942 03 41	Bosch Rexroth-Korea Ltd. Electric Drives and Controls Bongwoo Bldg. 7FL, 31-7, 1Ga Jangchoong-dong, Jung-gu Seoul, 100-391 Tel.: +82 234 061 813 Fax: +82 222 641 295	
Korea	Malaysia	Singapore - Singapur	South Africa - Südafrika	
Bosch Rexroth-Korea Ltd. 1515-14 Dadae-Dong, Saha-gu Electric Drives & Controls Pusan Metropolitan City, 604-050 Tel.: +82 51 26 00 741 Fax: +82 51 26 00 747 eunkyong.kim@boschrexroth.co.kr	Bosch Rexroth Sdn.Bhd. 11, Jalan U8/82, Seksyen U8 40150 Shah Alam Selangor, Malaysia Tel.: +60 3 78 44 80 00 Fax: +60 3 78 45 48 00 hockhwa@hotmail.com rexroth1@tm.net.my	Bosch Rexroth Pte Ltd 15D Tuas Road Singapore 638520 Tel.: +65 68 61 87 33 Fax: +65 68 61 18 25 sanjay.nemade @boschrexroth.com.sg	TECTRA Automation (Pty) Ltd. 71 Watt Street, Meadowdale Edenvale 1609 Tel.: +27 11 971 94 00 Fax: +27 11 971 94 40 Hotline: +27 82 903 29 23 georgy@tectra.co.za	
Taiwan	Thailand			
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12.5.5 Nordamerika - North America

USA	USA Central Region - Mitte	USA Southeast Region - Südwest	USA SERVICE-HOTLINE	
Bosch Rexroth Corporation Electric Drives & Controls 5150 Prairie Stone Parkway Hoffman Estates, IL 60192-3707 Tel.: +1 847 6 45 36 00 Fax: +1 847 6 45 62 01 servicebrc@boschrexroth-us.com repairbrc@boschrexroth-us.com	Bosch Rexroth Corporation Electric Drives & Controls Central Region Technical Center 1701 Harmon Road Auburn Hills, MI 48326 Tel.: +1 248 3 93 33 30 Fax: +1 248 3 93 29 06	Bosch Rexroth Corporation Electric Drives & Controls Southeastern Technical Center 3625 Swiftwater Park Drive Suwanee, Georgia 30124 Tel.: +1 770 9 32 32 00 Fax: +1 770 9 32 19 03	- 7 days x 24hrs - +1-800-REX-ROTH +1 800 739 7684	
USA East Region - Ost	USA Northeast Region - Nordost	USA West Region – West		
Bosch Rexroth Corporation Electric Drives & Controls Charlotte Regional Sales Office 14001 South Lakes Drive Charlotte, North Carolina 28273 Tel.: +1 704 5 83 97 62 +1 704 5 83 14 86	Bosch Rexroth Corporation Electric Drives & Controls Northeastern Technical Center 99 Rainbow Road East Granby, Connecticut 06026 Tel.: +1 860 8 44 83 77 Fax: +1 860 8 44 85 95	Bosch Rexroth Corporation 7901 Stoneridge Drive, Suite 220 Pleasant Hill, California 94588 Tel.: +1 925 227 10 84 Fax: +1 925 227 10 81		
Canada East - Kanada Ost	Canada West - Kanada West	Mexico	Mexico	
Bosch Rexroth Canada Corporation Burlington Division 3426 Mainway Drive Burlington, Ontario Canada L7M 1A8	Bosch Rexroth Canada Corporation 5345 Goring St. Burnaby, British Columbia Canada V7J 1R1	Bosch Rexroth Mexico S.A. de C.V. Calle Neptuno 72 Unidad Ind. Vallejo 07700 Mexico, D.F.	Bosch Rexroth S.A. de C.V. Calle Argentina No 3913 Fracc. las Torres 64930 Monterrey, N.L.	
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12.5.6 Südamerika - South America

Argentina - Argentinien	Argentina - Argentinien	Brazil - Brasilien	Brazil - Brasilien
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